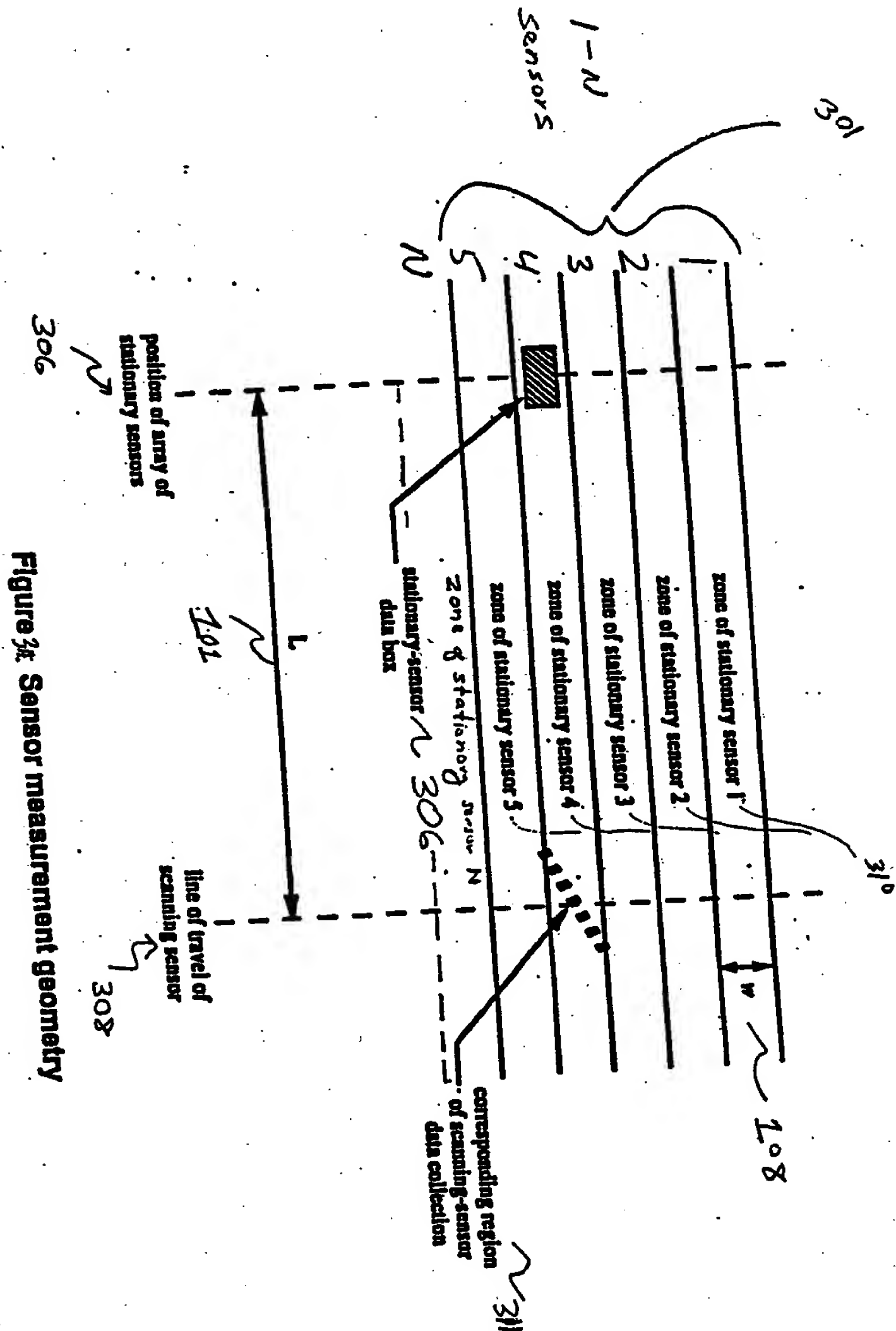


Figure 2: Overall system level diagram for the functions of the Data Fusion application.



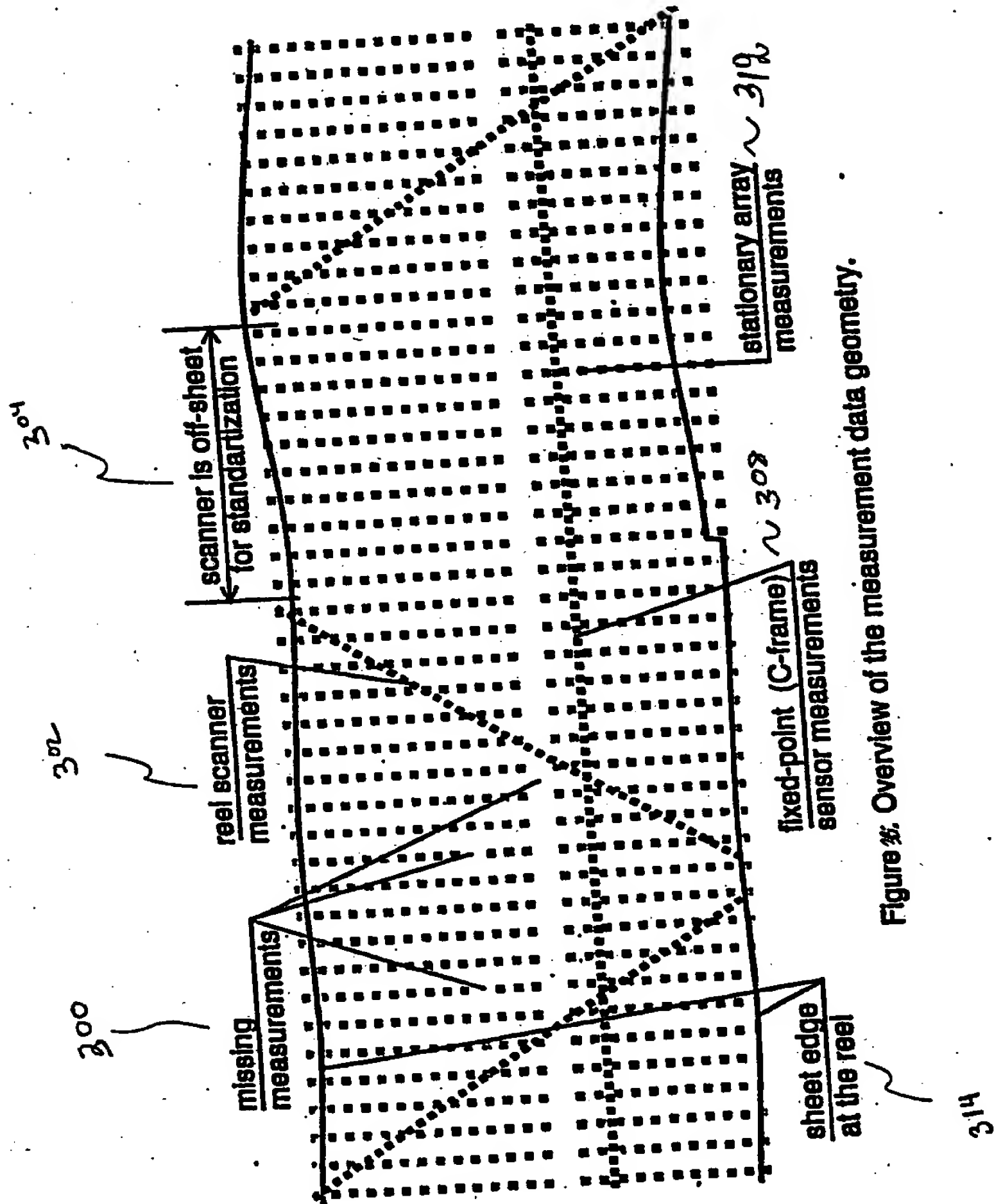


Figure 3. Overview of the measurement data geometry.

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INVENTOR(S): MARIO IGNAGNI ET AL

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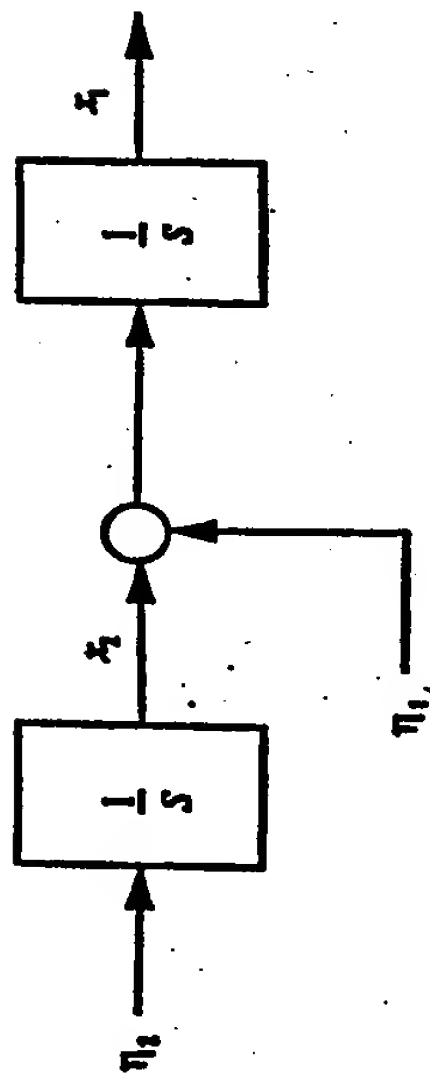


Figure 4: Dynamical model for sensor bias

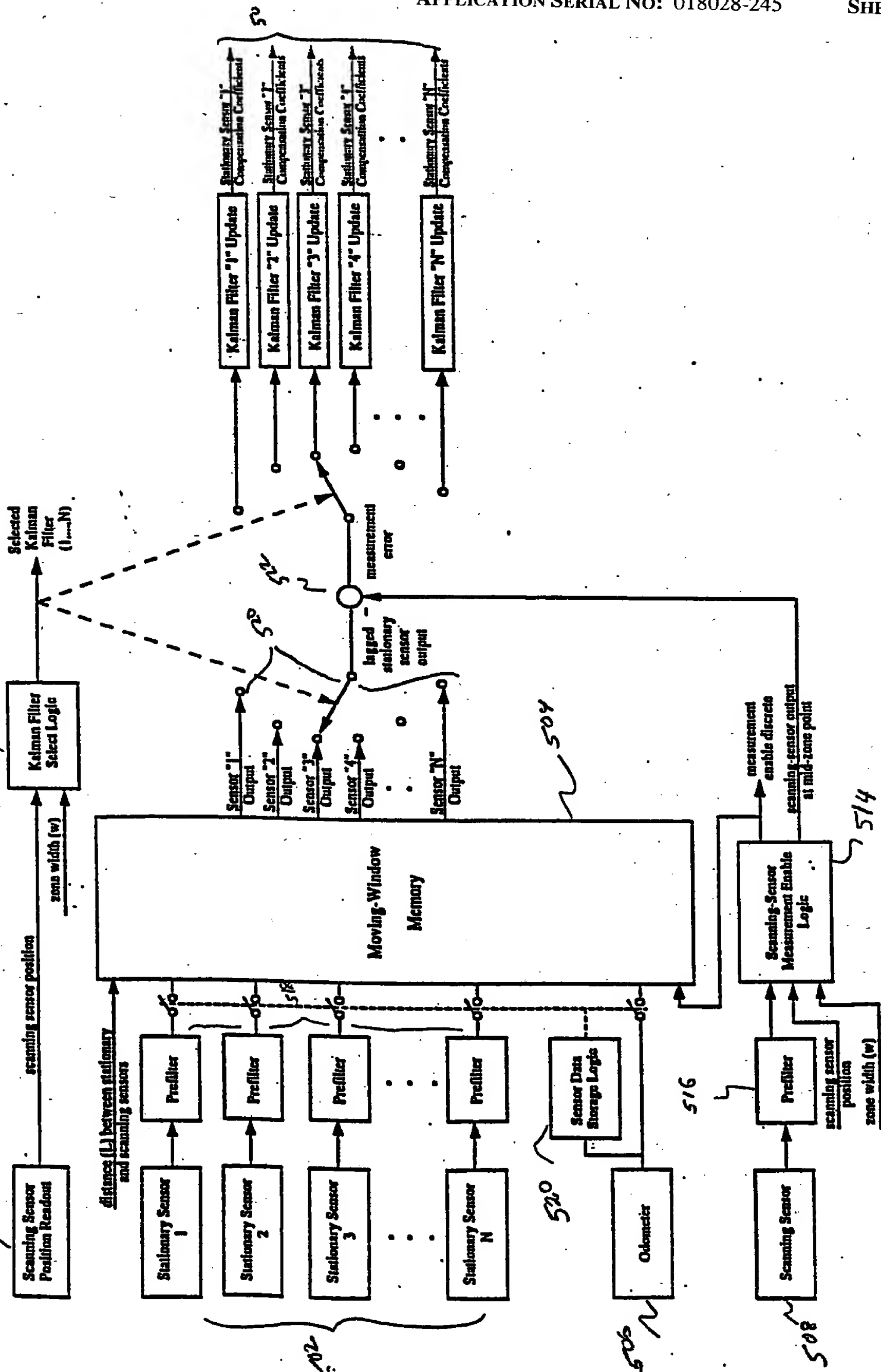


Figure 5: Stationary Sensor Bias Identification Concept

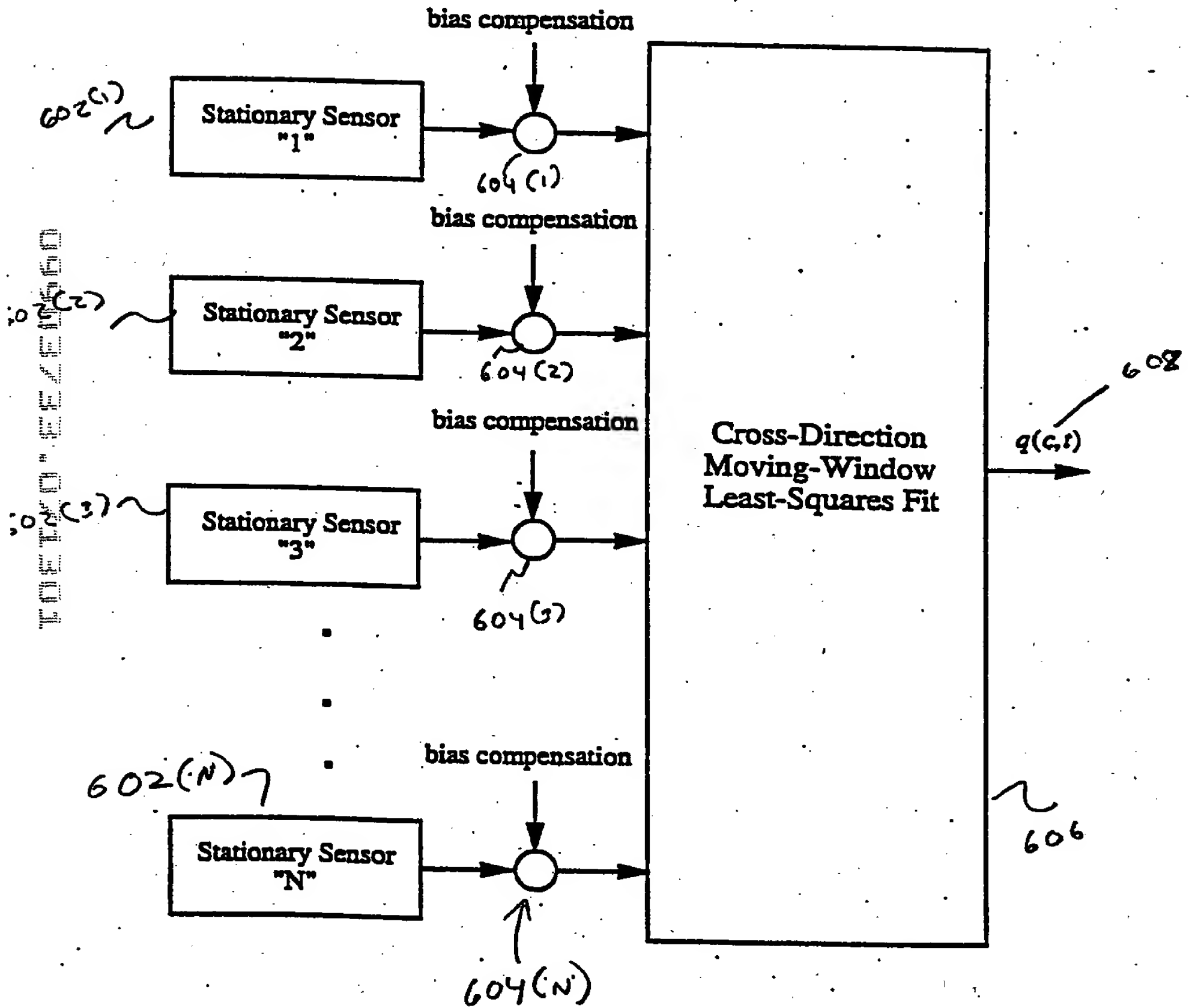


Figure 6: Moving-Window Least-Squares Processing to Derive Continuous CD Paper Parameter Variation as a Function of Time